

# ERF2026 Late breaking results poster session schedule

Date: Tuesday, 24 March

Location: Forum Deli, Forum Expo

## Dear LBR presenters:

1. Please display your poster in the Forum Deli before each poster session (5-10 minutes before)
2. LBR poster session
  - Session I (Paper ID 85 - 97): **10:30 -11:10**
  - Session II (Paper ID 98 -108): **15:20 -16:00**
3. Take down the poster after the session

(Please prepare your poster before the ERF, no printing service provided on site.)

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Session I (Paper ID 85 - 97): **10:30 -11:10** (during coffee break)

Paper ID	Paper Title	Primary Contact Author Name
85	Towards Developing Standards and Guidelines for Robot Grasping and Manipulation Pipelines in the COMPARE Ecosystem	Adam Norton
87	Evaluating robots and their safety in public spaces — standards, test pieces and examinations	Sven Schneider
88	UAV approach for Indoor Warehouse Inventory Operations	André Dias
90	Automatic reconfiguration of robot paths for zero defect manufacturing processes	Daniela Kirchberger
92	The Quest for Diversity in Human-Robot Communication	Jennifer Renoux
93	Multimodal User-Aware Dialogue Architecture Based on LLMs	Alessandra Sorrentino
94	Active vs. Passive Exoskeletons: Unlocking Sector-Specific Potential Across Work Domains	Cecilia Scoccia
95	AI-Driven Robotics for Textile Recycling: Enhancing Fiber Detection and Accessory Removal	Tony Ferreira
96	Evaluating Children Engagement and Robot Perception interacting with NAO robot in Educational Context: a Feasibility Study.	Laura Fiorini
97	CARGO: Container-unloading Autonomous Robot Pipeline	Manuel Fernando Dos Santos

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Session II (Paper ID 98 - 108): **15:20 -16:00** (during coffee break)

Paper ID	Paper Title	Primary Contact Author Name
89	ROBO-KNOT & INSIGHT: KNOWLEDGE TRANSFER PROJECTS TO BOOST COLLABORATION BETWEEN ACADEMIA AND INDUSTRY	Angel Dacal-Nieto
98	Rail-type and Tethered UAV multi-robotic system for autonomous bridge visual inspection	Nahuel Jose
99	A GAN-based Socially Assistive Robot Support for Paediatric Venipuncture: Co-Design and Preliminary Findings	Elena Adelucci
100	Imitation Learning for Human-Robot Collaborative Battery Disassembly: A Comprehensive Review	Cecilia Scoccia
101	A Socially Assistive Robotic Coach for Quantitative Fugl-Meyer Assessment in Post-Stroke Rehabilitation	Laura Fiorini
102	Human-Robot Communication needs Deliberation!	Kiran Sabu
103	Modular Multi-Robot Teleoperation System for Remote Supervision and Intervention	Manuel Couto
104	XR-based Robot Teaching for Manipulation Tasks	Marcelo Petry
105	EuroCore - Robotics on the European AI on Demand Platform	Uwe Kockemann
106	Pallet and Pocket Detection is Here!	Daniele Caldana
107	REISAR: Multi-Sensor Robot Inspection for Sewer Tunnel Network	Aouni Mejri
108	A Multi-Objective Approach to Sustainable and Human-Centric Manufacturing	Fernando Castaño